

1 We thank all the reviewers for their insightful comments! All the responses will be incorporated into our revision.

2 **R1: (1)** We designed a variational graph isomorphism network to injectively encode structural information of networks
 3 in the latent space and accurately remap to original structures after latent space optimization. **(2)** The observations are
 4 pretrained embeddings of the selected neural architectures. **(3)** The searched networks are trained from scratch.

5 **R2: (1)** Details of supervised learning approach: architecture embeddings and search strategies (e.g., BO) are jointly
 6 optimized in a supervised manner. The supervision signal for embedding learning comes from the accuracies of
 7 architectures selected by the search strategies. In addition to accuracy, NAO takes the reconstruction loss of \hat{A} and \hat{X}
 8 into account. However, as reported in our submission or Table 1 below, its performance is inferior to our unsupervised
 9 approach as it cannot necessarily improve embedding learning due to entangling structure reconstruction and accuracy
 10 prediction together. **(2)** Superiority of pretrained embeddings: compared to supervised embeddings, the pretrained
 11 embeddings are able to better capture the structural information (e.g. edit distance measures) of neural networks. This
 12 is because the optimization objective in pretraining is structure reconstruction only. As we showed in Figure 3 and 4
 13 in the submission, compared to supervised learning, pretraining makes similar architectures clustered better (Figure
 14 3), and hence the accuracies are clustered and distributed more smoothly in the latent space (Figure 4). Conducting
 15 architecture search in such smooth performance surface is much easier and is hence more efficient. Note that we only
 16 use the accuracy of architecture as supervision in the search phase. **(3)** How pretrained embeddings are used with BO
 17 and RL for architecture search: for BO, the pretrained embeddings are passed to Bayesian optimization algorithm
 18 (DNGO) to select the top-K architectures in each round of search. For RL, the pretrained embeddings are passed to the
 19 Policy LSTM to sample the action and obtain the next state (valid architecture embedding) using nearest-neighborhood
 20 retrieval to maximize accuracy as reward. We covered some details in Supplementary A. We will add a thorough
 21 description of how pretrained embeddings are used with search strategies in the revision. **(4)** Fine-tuning: we did not
 22 fine-tune the embeddings during search based on the performance of the architectures. This is also because it biases
 23 the structural clustering obtained from pretraining, which leads to inferior search performance. We will add this result
 24 in the revised version. **(5)** Colorscale jumps (red and black) in Figure 4: we overlaid the original colorscale with red
 25 ($>92\%$ accuracy) and black ($<82\%$ accuracy) for highlighting purpose. **(6)** Naming observations: we will name our
 26 observations to reflect their nature in the revision. **(7)** Reproducibility: to facilitate fully reproducing our results, we
 27 attached the source code in our submitted supplementary material.

28 **R3: (1)** We report the result of GD on NAS101 in terms of test regret in Figure
 29 1 and number of samples in Table 1. We have two observations. First, for
 30 GD, NAS with pretrained embeddings outperforms supervised embeddings.
 31 This aligns with our results in RL and BO. Second, GD performs worse than
 32 RL and BO in both unsupervised and supervised methods. This could be
 33 attributed to how GD minimizes the prediction error, which could easily enter
 34 the local minimum. We will add this result in the revised version. **(2)** Supervised
 35 embeddings are less capable of preserving the structural information due to the
 36 learning bias introduced by predicted accuracy, and thus are distributed less
 37 smoothly in the latent space which results in more overlapped (or blank) areas.

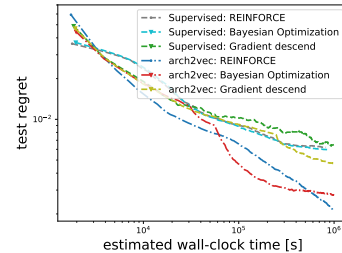


Figure 1: Test regret of GD & others.

38 **(3)** Thanks for suggesting [1,2]. [1] focuses on network generators that output relational graphs, and the predictive
 39 performance highly depends on the structure measures of the relational graphs. In contrast, we encode structural
 40 information of neural networks into compact continuous embeddings, and the predictive performance depends on how
 41 well the structure is injected into the embeddings. [2] focuses on transforming adjacency matrix-based encoding to
 42 path-based encoding in the discrete space. In contrast, we focus on encoding adjacency matrix-based architectures to
 43 low-dimensional embeddings in the continuous space. We will add the discussions on [1,2] in the revised version.

44 **R4: (1)** Thanks for suggesting the related work. While the related work
 45 tackles the generative problems, our work focuses on mapping the finite
 46 discrete neural architectures into the continuous latent space regularized
 47 by KL-divergence such that each architecture is encoded into a unique
 48 area in the latent space. Importantly, we systematically investigate how
 49 pretraining preserves the structure of neural networks and affects their
 50 predictive performance in NAS. We will emphasize this distinction in the
 51 revised version. **(2)** The KL term is used to regularize the mapping from the discrete space to the continuous latent
 52 space. It helps to perform a better inference and to preserve the validity performance of the model. We show the
 53 effectiveness of using KL for pretraining on three search spaces in Table 2 below. We will add this result in the revision.

NAS Methods	#Queries	Accuracy (%)	Encoding	Search Method
NAO	1000	93.74	Supervised	GD
GD (ours)	400	93.69	Supervised	GD
RL (ours)	400	93.74	Supervised	REINFORCE
BO (ours)	400	93.79	Supervised	BO
arch2vec-GD	400	93.85	Unsupervised	GD
arch2vec-RL	400	94.10	Unsupervised	REINFORCE
arch2vec-BO	400	94.05	Unsupervised	BO

Table 1: Number of samples of GD & others.

Method	NAS-Bench-101			NAS-Bench-201			DARTS		
	Accuracy	Validity	Uniqueness	Accuracy	Validity	Uniqueness	Accuracy	Validity	Uniqueness
arch2vec (w.o. KL)	100	30.31	99.20	100	77.09	96.57	99.46	16.01	99.51
arch2vec	100	51.33	99.36	100	79.41	98.72	99.79	33.36	100

Table 2: An ablation study on the effectiveness of KL for pretraining.