

1 We thank three reviewers for the constructive comments. We are especially happy that they think the paper contains  
2 strong and interesting results. In what follows we make a few clarifications and itemized responses.

### 3 **Novelty of our work:**

4 • We are the first to bring the perspective of NMF/topic modeling to Markov state aggregation. Even though the idea  
5 is not hard to understand, *no one has investigated it*. Prior to our work, there are no existing methods that can directly  
6 estimate the aggregation/disaggregation distributions with theoretical guarantees. Our work opens the door of bridging  
7 two areas. We hope our work would inspire future work and more efficient methods may be developed.

8 • Making this idea work, both in theory and in applications, requires substantial efforts and nontrivial analysis. The  
9 devil is in the detail. In theory, the entry-wise eigenvector analysis, particularly needed for state aggregation learning, is  
10 very challenging. This result per se is significant and provides a technical tool that may be useful for the analysis of a  
11 broader class of spectral/NMF methods. In application, we not only obtain encouraging results on Manhattan taxi data  
12 but also demonstrate the method is useful for accelerating policy learning.

### 13 **Response to Reviewer #1**

14 • *“Will similar results hold for a straightforward combination of existing estimators of transition matrix (e.g., [28])  
15 and existing topic modeling methods (e.g. [4])?”*

16 **RE:** Good point. In fact, straightforward application of [4] would yield a slower rate of convergence. The reason is that  
17 “translating” our problem to a topic model would result in a special case where the dictionary size is equal to the number  
18 of documents. Unfortunately, in this case, [4] has a sub-optimal rate of convergence (see [22]). Combining [4] with the  
19 estimator in [28] is a good idea, but whether it resolves the sub-optimality issue remains unclear. Additionally, our  
20 method has a practical advantage: It operates on the projected data by PCA and is computationally fast. In contrast, a  
21 combination of [28] and [4] would require handling data in high dimensions, which is computationally more intensive.  
22 Besides, this is only a potential proposal, not an existing method. We agree that it is very interesting to explore all kinds  
23 of possibilities in the context of our framework, but it is beyond the scope of this paper.

24 • *“Why not consider sampling from the trajectory and reduce it to a standard topic model?”*

25 **RE:** Downsampling the trajectory was exactly what we did in the previous version of this paper. However, this  
26 simplified approach received many criticisms. By resampling from the trajectory, we lose the sample size by a constant  
27 factor. In practice, the sample size is often limited compared to the dimension, and discarding even a fraction of samples  
28 can significantly deteriorate the accuracy. Additionally, the downsampling approach requires knowledge of the mixing  
29 time or at least its lower bound, which is often not known and becomes an additional tuning parameter. Resampling  
30 from the trajectory is only a way to avoid technical difficulty of theorem proving. In practice, people would almost  
31 always use all the data without downsampling. We prefer not to have such a gap between theory and application.

32 • *“It there any minimax lower bound?”*

33 **RE:** As mentioned in Lines 264-266, there exists a lower bound for  $r = 1$ . To obtain a lower bound for  $r > 1$  is very  
34 interesting, but it is beyond the scope of this paper. This paper aims to provide an algorithm with provable guarantees.

35 • *“Better explanation of the connection to related work.”*

36 **RE:** Thanks for the nice suggestion. In the submission, we summarized the connection to related works in state  
37 aggregation, spectral methods, estimating transition matrix, learning mixtures of discrete distributions, topic modeling,  
38 and NMF. See Section 1 and the end of Section 4. We will follow your suggestion to re-arrange and expand them.

### 39 **Response to Reviewer #3**

40 • *“Improvement on writing, such as to expand the section of “connection to literatures”, to shorten “our contributions”,  
41 to re-arrange Sections 3 and 4, and to mention some proof ideas)”*

42 **RE.** Thank you for these great suggestions! We will follow them to improve the writing.

43 • *“More discussions on Assumptions (a)-(e).”*

44 **RE.** Thank you. We kept the discussions short due to space limit. We used to have extensive discussions on these  
45 assumptions in a previous version of the paper, and we will add them back. We are glad that you see merits in our paper  
46 and we will improve the writing and organization as you suggested.

### 47 **Response to Reviewer #4**

48 • *“Difference from standard spectral methods.”*

49 **RE:** Thank you for seeing the merit in our paper. The state aggregation model has richer structure than just spectral  
50 decomposition (eg., polytope structure, anchor states and nonnegativity). In Lines 153-162, we show that each left/right  
51 singular vector is a linear combination of multiple disaggregation/aggregation distributions, however they cannot be  
52 used to immediately identify the disaggregation/aggregation distributions. This is why we need to use anchor states to  
53 help us identify the simplex structure of the state space. The key idea of our method is to leverage the anchor structure  
54 and “combine” multiple singular vectors to get a valid estimate of an individual aggregation/disaggregation distribution.  
55 As a result, our method needs to perform several non-trivial steps after performing singular value decomposition.  
56 Experiments with Manhattan taxi data also clearly shows the comparison between our method and standard spectral  
57 method.